

CHAPTER 14

Inductance



Figure 14.1 A smartphone charging mat contains a coil that receives alternating current, or current that is constantly increasing and decreasing. The varying current induces an emf in the smartphone, which charges its battery. Note that the black box containing the electrical plug also contains a transformer (discussed in [Alternating-Current Circuits](#)) that modifies the current from the outlet to suit the needs of the smartphone. (credit: modification of work by “LG”/Flickr)

Chapter Outline

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INTRODUCTION In [Electromagnetic Induction](#), we discussed how a time-varying magnetic flux induces an emf in a circuit. In many of our calculations, this flux was due to an applied time-dependent magnetic field. The reverse of this phenomenon also occurs: The current flowing in a circuit produces its own magnetic field.

In [Electric Charges and Fields](#), we saw that induction is the process by which an emf is induced by changing electric flux and separation of a dipole. So far, we have discussed some examples of induction, although some of these applications are more effective than others. The smartphone charging mat in the chapter opener photo also works by induction. Is there a useful physical quantity related to how “effective” a given device is? The answer is yes, and that physical quantity is *inductance*. In this chapter, we look at the applications of inductance in electronic devices and how inductors are used in circuits.

14.1 Mutual Inductance

Learning Objectives

By the end of this section, you will be able to:

- Correlate two nearby circuits that carry time-varying currents with the emf induced in each circuit
- Describe examples in which mutual inductance may or may not be desirable

Inductance is the property of a device that tells us how effectively it induces an emf in another device. In other words, it is a physical quantity that expresses the effectiveness of a given device.

When two circuits carrying time-varying currents are close to one another, the magnetic flux through each circuit varies because of the changing current I in the other circuit. Consequently, an emf is induced in each circuit by the changing current in the other. This type of emf is therefore called a *mutually induced emf*, and the phenomenon that occurs is known as **mutual inductance (M)**. As an example, let’s consider two tightly wound coils ([Figure 14.2](#)). Coils 1 and 2 have N_1 and N_2 turns and carry currents I_1 and I_2 , respectively. The flux through a single turn of coil 2 produced by the magnetic field of the current in coil 1 is Φ_{21} , whereas the flux through a single turn of coil 1 due to the magnetic field of I_2 is Φ_{12} .

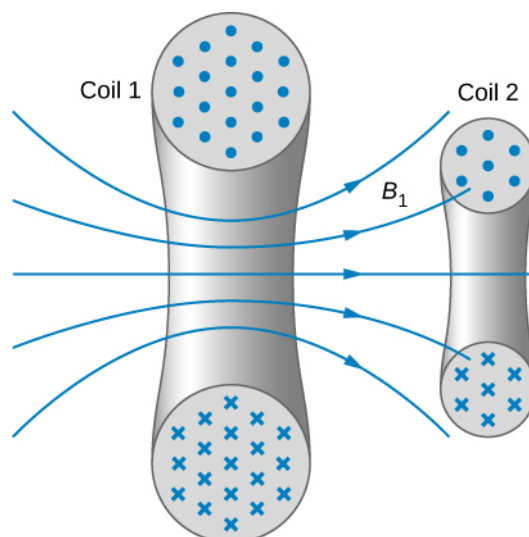


Figure 14.2 Some of the magnetic field lines produced by the current in coil 1 pass through coil 2.

The mutual inductance M_{21} of coil 2 with respect to coil 1 is the ratio of the flux through the N_2 turns of coil 2 produced by the magnetic field of the current in coil 1, divided by that current, that is,

$$M_{21} = \frac{N_2 \Phi_{21}}{I_1}. \quad 14.1$$

Similarly, the mutual inductance of coil 1 with respect to coil 2 is

$$M_{12} = \frac{N_1 \Phi_{12}}{I_2}. \quad 14.2$$

Like capacitance, mutual inductance is a geometric quantity. It depends on the shapes and relative positions of the two coils, and it is independent of the currents in the coils. The SI unit for mutual inductance M is called the **henry (H)** in honor of Joseph Henry (1799–1878), an American scientist who discovered induced emf independently of Faraday. Thus, we have $1 \text{ H} = 1 \text{ V} \cdot \text{s/A}$. From [Equation 14.1](#) and [Equation 14.2](#), we can show that $M_{21} = M_{12}$, so we usually drop the subscripts associated with mutual inductance and write

$$M = \frac{N_2 \Phi_{21}}{I_1} = \frac{N_1 \Phi_{12}}{I_2}. \quad 14.3$$

The emf developed in either coil is found by combining Faraday's law and the definition of mutual inductance. Since $N_2 \Phi_{21}$ is the total flux through coil 2 due to I_1 , we obtain

$$\varepsilon_2 = -\frac{d}{dt}(N_2 \Phi_{21}) = -\frac{d}{dt}(M I_1) = -M \frac{dI_1}{dt} \quad 14.4$$

where we have used the fact that M is a time-independent constant because the geometry is time-independent. Similarly, we have

$$\varepsilon_1 = -M \frac{dI_2}{dt}. \quad 14.5$$

In [Equation 14.5](#), we can see the significance of the earlier description of mutual inductance (M) as a geometric quantity. The value of M neatly encapsulates the physical properties of circuit elements and allows us to separate the physical layout of the circuit from the dynamic quantities, such as the emf and the current. [Equation 14.5](#) defines the mutual inductance in terms of properties in the circuit, whereas the previous definition of mutual inductance in [Equation 14.1](#) is defined in terms of the magnetic flux experienced, regardless of circuit elements. You should be careful when using [Equation 14.4](#) and [Equation 14.5](#) because ε_1 and ε_2 do not necessarily represent the total emfs in the respective coils. Each coil can also have an emf induced in it because of its *self-inductance* (self-inductance will be discussed in more detail in a later section).

A large mutual inductance M may or may not be desirable. We want a transformer to have a large mutual inductance. But an appliance, such as an electric clothes dryer, can induce a dangerous emf on its metal case if the mutual inductance between its coils and the case is large. One way to reduce mutual inductance is to counter-wind coils to cancel the magnetic field produced ([Figure 14.3](#)).

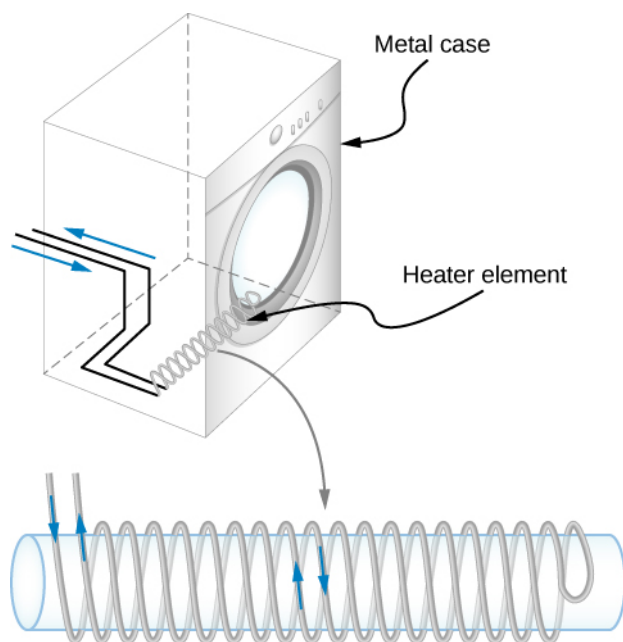


Figure 14.3 The heating coils of an electric clothes dryer can be counter-wound so that their magnetic fields cancel one another, greatly reducing the mutual inductance with the case of the dryer.

Digital signal processing is another example in which mutual inductance is reduced by counter-winding coils. The rapid on/off emf representing 1s and 0s in a digital circuit creates a complex time-dependent magnetic field. An emf can be generated in neighboring conductors. If that conductor is also carrying a digital signal, the induced emf may be large enough to switch 1s and 0s, with consequences ranging from inconvenient to disastrous.

EXAMPLE 14.1

Mutual Inductance

Figure 14.4 shows a coil of N_2 turns and radius R_2 surrounding a long solenoid of length l_1 , radius R_1 , and N_1 turns. (a) What is the mutual inductance of the two coils? (b) If $N_1 = 500$ turns, $N_2 = 10$ turns, $R_1 = 3.10$ cm, $l_1 = 75.0$ cm, and the current in the solenoid is changing at a rate of 200 A/s, what is the emf induced in the surrounding coil?

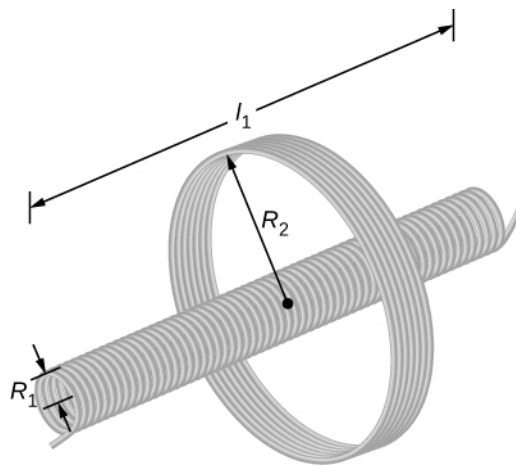


Figure 14.4 A solenoid surrounded by a coil.

Strategy

There is no magnetic field outside the solenoid, and the field inside has magnitude $B_1 = \mu_0(N_1/l_1)I_1$ and is

directed parallel to the solenoid's axis. We can use this magnetic field to find the magnetic flux through the surrounding coil and then use this flux to calculate the mutual inductance for part (a), using [Equation 14.3](#). We solve part (b) by calculating the mutual inductance from the given quantities and using [Equation 14.4](#) to calculate the induced emf.

Solution

- a. The magnetic flux Φ_{21} through the surrounding coil is

$$\Phi_{21} = B_1 \pi R_1^2 = \frac{\mu_0 N_1 I_1}{l_1} \pi R_1^2.$$

Now from [Equation 14.3](#), the mutual inductance is

$$M = \frac{N_2 \Phi_{21}}{I_1} = \left(\frac{N_2}{I_1} \right) \left(\frac{\mu_0 N_1 I_1}{l_1} \right) \pi R_1^2 = \frac{\mu_0 N_1 N_2 \pi R_1^2}{l_1}.$$

- b. Using the previous expression and the given values, the mutual inductance is

$$\begin{aligned} M &= \frac{(4\pi \times 10^{-7} \text{ T}\cdot\text{m/A})(500)(10)\pi(0.0310 \text{ m})^2}{0.750 \text{ m}} \\ &= 2.53 \times 10^{-5} \text{ H}. \end{aligned}$$

Thus, from [Equation 14.4](#), the emf induced in the surrounding coil is

$$\begin{aligned} \varepsilon_2 &= -M \frac{dI_1}{dt} = -(2.53 \times 10^{-5} \text{ H})(200 \text{ A/s}) \\ &= -5.06 \times 10^{-3} \text{ V}. \end{aligned}$$

Significance

Notice that M in part (a) is independent of the radius R_2 of the surrounding coil because the solenoid's magnetic field is confined to its interior. In principle, we can also calculate M by finding the magnetic flux through the solenoid produced by the current in the surrounding coil. This approach is much more difficult because Φ_{12} is so complicated. However, since $M_{12} = M_{21}$, we do know the result of this calculation.

✓ CHECK YOUR UNDERSTANDING 14.1

A current $I(t) = (5.0 \text{ A}) \sin((120\pi \text{ rad/s})t)$ flows through the solenoid of part (b) of [Example 14.1](#). What is the maximum emf induced in the surrounding coil?

14.2 Self-Inductance and Inductors

Learning Objectives

By the end of this section, you will be able to:

- Correlate the rate of change of current to the induced emf created by that current in the same circuit
- Derive the self-inductance for a cylindrical solenoid
- Derive the self-inductance for a rectangular toroid

Mutual inductance arises when a current in one circuit produces a changing magnetic field that induces an emf in another circuit. But can the magnetic field affect the current in the original circuit that produced the field? The answer is yes, and this is the phenomenon called *self-inductance*.

Inductors

[Figure 14.5](#) shows some of the magnetic field lines due to the current in a circular loop of wire. If the current is constant, the magnetic flux through the loop is also constant. However, if the current I were to vary with time—say, immediately after switch S is closed—then the magnetic flux Φ_m would correspondingly change. Then Faraday's law tells us that an emf ε would be induced in the circuit, where

$$\varepsilon = - \frac{d\Phi_m}{dt}. \quad 14.6$$