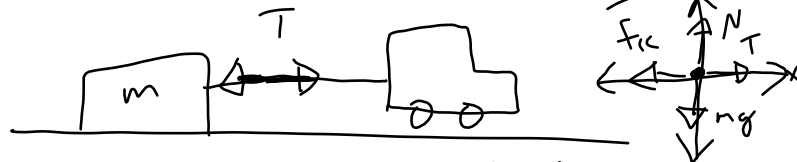


Units for work (and hence, energy) are Joules

$$W = \int \vec{F} \cdot d\vec{r} \quad \text{units of } N \cdot m = J = \frac{kg \cdot m^2}{s^2}$$

Example with friction



A large mass is pulled by a truck  
a distance  $\Delta x$  against friction (force  $f_k$ ).  
If  $\vec{T} = \text{constant}$ , then

$$W_{\text{truck}} = \vec{T} \cdot \Delta x \hat{i} = T \Delta x$$

$$W_{\text{friction}} = -f_k \Delta x$$

$$W_{\text{net}} = W_{\text{truck}} + W_{\text{friction}} = (T - f_k) \Delta x$$

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Work-KE Thm

$$W_{\text{net}} = \Delta K = \frac{1}{2} m v_f^2 - \frac{1}{2} m v_i^2$$

$$K_f - K_i$$

If we know (or calculate)  $T$  and  $f_k$ ,  
we can find  $v_f$  given  $v_i$

consider 2 situations:

(i) No net force on mass

$$\sum F_x = 0 \rightarrow T - f_k = 0 \rightarrow T = f_k$$

$$\sum F_y = 0 \rightarrow N - mg = 0 \rightarrow N = mg$$

$$W_{\text{net}} = (T - f_k) \Delta x = 0$$

$$v_f = v_i = \text{constant} \rightarrow v_x = \text{constant}$$

We already knew this because

$$\vec{a} = 0, \vec{v} = \text{constant}$$

\* If there is no net force, then there  
is no change in kinetic energy

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Suppose in case (i), we had  $\Delta x = 100 \text{ m}$   
 $\mu_k = 0.25$ ,  $m = 200 \text{ kg}$ ,  $v_i = 3.2 \text{ m/s}$

$$\text{Then } F_k = \mu_k N = \mu_k mg = 500 \text{ N}$$

$$\text{So } T = 500 \text{ N too}$$

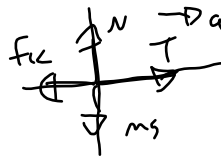
And, since  $v = \text{constant}$ ,

$$\Delta x = v \Delta t \rightarrow \Delta t = \frac{\Delta x}{v} = \frac{100 \text{ m}}{3.2 \text{ m/s}}$$

$$\Delta t = 32 \text{ s}$$

(ii) Suppose same frictional force, same initial velocity, same mass, but we pull with tension  $T = 600 \text{ N}$

FBD for mass



$$T - f_k = m a_x$$

$$a_x = \frac{100 \text{ N}}{200 \text{ kg}} = 0.5 \text{ m/s}^2$$

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Now we have

$$W_{\text{net}} = (F - f_k) \Delta x$$

$$= (100 \text{ N})(100 \text{ m}) = 10^4 \text{ J}$$

note from before,  $v_i = 3.2 \text{ m/s}$

$$K_i = \frac{1}{2} m v_i^2 = \frac{200 \text{ kg}}{2} (3.2 \text{ m/s})^2$$

$$= 10^3 \text{ J}$$

$$W_{\text{net}} = K_f - K_i \rightarrow K_f = W_{\text{net}} + K_i$$

$$\frac{1}{2} m v_f^2 = 1.1 \times 10^4 \text{ J}$$

$$v_f = \sqrt{\frac{2}{m} (1.1 \times 10^4 \text{ J})} = \sqrt{110 \frac{\text{m}^2}{\text{s}^2}} = 10.5 \text{ m/s}$$

Note from the kinematic equations

$$v_x^2 = v_{x0}^2 + 2 a_x \Delta x$$

$$v_x = \sqrt{(3.2 \text{ m/s})^2 + 2(0.5 \text{ m/s}^2)(100 \text{ m})}$$

$$= \sqrt{110 \text{ m}^2/\text{s}^2} = 10.5 \text{ m/s}$$

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Power  $P = \frac{dW}{dt} = \text{rate of doing work}$

In previous example, we could find the mean power delivered by the track

$$\bar{P} = \frac{\Delta W_{\text{track}}}{\Delta t} \quad \text{not the same as } W_{\text{net}}$$

in case (i), we had  $W_{\text{net}} = 0$  on mass ← net work done

$$\Delta W_{\text{track}} = (500 \text{ N})(100 \text{ m}) = 5 \times 10^4 \text{ J}$$

$$\bar{P} = \frac{\Delta W_{\text{track}}}{\Delta t} = \frac{5 \times 10^4 \text{ J}}{32 \text{ s}} = 1.6 \times 10^3 \frac{\text{J}}{\text{s}}$$

Watt

in case (ii)

$$\Delta W_{\text{track}} = (600 \text{ N})(100 \text{ m}) = 6 \times 10^4 \text{ J}$$

$$\bar{P} = \frac{6 \times 10^4 \text{ J}}{\Delta t} \quad \text{Need } \Delta t \text{ for case (ii)}$$

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$$a_x = 0.5 \text{ m/s}^2$$

$$v_x = v_{x0} + a_x \Delta t$$

$$\Delta t = \frac{v_x - v_{x0}}{a_x} = \frac{10.5 \text{ m/s} - 3.2 \text{ m/s}}{0.5 \text{ m/s}^2}$$

$$= 14.6 \text{ s} \quad (\text{much shorter})$$

$$\bar{P} = \frac{6 \times 10^4 \text{ J}}{14.6 \text{ s}} = 4.1 \times 10^3 \text{ W}$$

(recall from case (i)  $\bar{P} = 1.6 \times 10^3 \text{ W}$ )

There is another expression for P that is sometimes useful (usually when  $\vec{v} = \text{const.}$ )

$$P = \frac{dW}{dt} = \frac{\vec{F} \cdot d\vec{r}}{dt} = \vec{F} \cdot \frac{d\vec{r}}{dt} = \vec{F} \cdot \vec{v}$$

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Previous example, for case (i),  
 $v = \text{constant} = 3.2 \text{ m/s}$   
 $F = \text{constant} = 500 \text{ N}$   
 $\bar{p} = (500 \text{ N})(3.2 \text{ m/s}) = 1.6 \times 10^3 \frac{\text{N}\cdot\text{m}}{\text{s}}$

Potential Energy

For some forces (such as gravity, springs, electrostatic), we can define a potential energy

$\Delta U_{AB} = U_B - U_A = -W_{AB}$

Important:  
 Only changes in  $U$  are physically relevant

net work done on an object, with no dissipation

$\frac{\text{N}\cdot\text{m}}{\text{s}}$   
 $\frac{\text{J}}{\text{s}}$   
 $\frac{\text{W}}{\text{W}}$

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Types of PE

1. Gravitational

$\Delta U_{\text{grav}} = -W_{AB} = mg(y_B - y_A)$

example

$\frac{1}{2}mv^2 = mgy_B$

$y_A = 0, U_A = 0$

$\Delta U_{\text{grav}} = mgy_B$

we will find in chapter 8.

$(E = K + U) = \text{constant}$  with no dissipation  
 where  $E = \text{total energy}$   
 conservation of energy

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